

# A New Fixed-Point Theorem for Logic Programming Semantics

Pascal Hitzler\* and Anthony K. Seda

Department of Mathematics, University College Cork  
Cork, Ireland

E-mail: {phitzler,aks}@ucc.ie

Web: <http://maths.ucc.ie/~{pascal,seda}>

## Abstract

We present a new fixed-point theorem akin to the Banach contraction mapping theorem, but in the context of a novel notion of generalized metric space, and show how it can be applied to analyse the denotational semantics of certain logic programs. The theorem is obtained by generalizing a theorem of Priess-Crampe and Ribenboim, which grew out of applications within valuation theory, but is also inspired by a theorem of S.G. Matthews which grew out of applications to conventional programming language semantics. The class of programs to which we apply our theorem was defined previously by us in terms of operators using three-valued logics. However, the new treatment we provide here is short and intuitive, and provides further evidence that metric-like structures are an appropriate setting for the study of logic programming semantics.

**Keywords:** Logic Programming, Denotational Semantics, Supported Model, Generalized Metric, Fixed-point Theorem

## Introduction

One advantage possessed by a logic program  $P$ , or a disjunctive database, over conventional imperative and object oriented programs is that it has a natural machine-independent meaning, namely, its logical meaning or declarative semantics. This is usually taken to be some “standard” model canonically associated with  $P$ . Unfortunately, there is often many possible choices

for the standard model such as the well-founded model (van Gelder et al.), the stable model (Gelfond and Lifschitz), the perfect and weakly perfect models (Przymusiński), and so on, which do not in general coincide and all of which have a claim to be “the natural choice” depending on one’s view of non-monotonic reasoning. It is therefore important and interesting to know when these various models coincide since this confirms coincidence of the various ways of considering non-monotonic reasoning.

In [6, 10], the authors defined certain classes of programs, called  $\Phi$ -accessible and  $\Phi^*$ -accessible programs, which have the property that each program in the class has a unique supported model, and showed that it follows from this property that all the different semantics mentioned above in fact coincide. These latter classes were defined in terms of various three-valued logics and are known to include the acceptable programs of Apt and Pedreschi (important in termination analysis), see [2], and certain other important classes, and are also known to be computationally adequate i.e. can compute all partial recursive functions; they therefore provide a semantically unambiguous setting with enhanced syntax and full computational power.

The supported models of  $P$  (or the Clark completion semantics) are the fixed points of the single-step operator  $T_P$ , and the proof of their existence and uniqueness we gave in [6] for the  $\Phi$ -accessible and  $\Phi^*$ -accessible programs was by means of three-valued logic. In this paper, we provide an alternative proof based on a new fixed-point theorem we establish here which generalizes the theorem of Priess-Crampe & Riben-

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boim [7, 14, 15]. This generalization was inspired by the occurrence of distance functions  $d$  with the slightly surprising property that  $d(x, x)$  need not be zero. Indeed, such distance functions have already been discussed by Matthews in [12, 13] in connection with the data flow networks of Kahn, and this suggests that theorems of the sort we present here may have other interesting applications within computer science.

## Preliminaries

A (*normal*) *logic program* is a finite set of universally quantified clauses, from first order logic, of the form

$$\forall (A \leftarrow L_1 \wedge \cdots \wedge L_n),$$

where  $A$  is an atom and  $L_1, \dots, L_n$  are literals. Such clauses are usually written as

$$A \leftarrow L_1, \dots, L_n.$$

We call  $A$  the *head* of the clause, and  $L_1, \dots, L_n$  the *body* of the clause. Each  $L_i$  is said to be a *body literal* of the clause. We refer to [11] for notation and basic concepts in logic programming.

For a given logic program  $P$ , we denote the Herbrand base (i.e. the set of all ground atoms in the underlying first order language) by  $B_P$ . As usual, (Herbrand-) interpretations of  $P$  can be identified with subsets of  $B_P$ , so that the set  $I_P$  of all interpretations of  $P$  can be identified with the power set of  $B_P$ . The set of all ground instances of each clause in a program  $P$  will be denoted by  $\text{ground}(P)$ . A *level mapping* is a function  $l : B_P \rightarrow \alpha$ , where  $\alpha$  is an arbitrary (countable) ordinal; we always assume that  $l$  has been extended to all literals by setting  $l(\neg A) = l(A)$  for each  $A \in B_P$ .

The standard approach to logic programming semantics, i.e. to assigning a reasonable meaning to a given logic program, is to identify models of the program which have certain additional properties. We will focus here on the *supported model semantics* or *Clark completion semantics*, see [4, 1]. We define the *immediate consequence* or *single-step operator*  $T_P$  for a given logic program  $P$  as a mapping  $T_P : I_P \rightarrow I_P$  of interpretations to interpretations as follows:  $T_P(I)$  is the

set of all  $A \in B_P$  such that there exists a ground instance  $A \leftarrow L_1, \dots, L_n$  of a clause in  $P$  with head  $A$  and such that  $I \models L_1 \wedge \cdots \wedge L_n$ . Note that  $T_P$  is in general not monotonic. As it turns out, the models of  $P$  are exactly the pre-fixed points of  $T_P$ , that is, satisfy  $T_P(I) \subseteq I$ . A *supported model* (or model of the Clark completion [4]) of  $P$  is a fixed point of  $T_P$ , see [11] for these and related concepts.

The following definition is taken from [2] where it was employed in defining acceptable programs. Such programs have been shown to be of great importance in termination analysis, and we will use it as the basis of the more general Definition 2.

**Definition 1** Let  $P$  be a logic program and let  $p, q$  be predicate symbols occurring in  $P$ .

1.  $p$  *refers to*  $q$  if there is a clause in  $P$  with  $p$  in its head and  $q$  in its body.
2.  $p$  *depends on*  $q$  if  $(p, q)$  is in the reflexive, transitive closure of the relation *refers to*.
3.  $\text{Neg}_P$  denotes the set of predicate symbols in  $P$  which occur in a negative literal in the body of a clause in  $P$ .
4.  $\text{Neg}_P^*$  denotes the set of all predicate symbols in  $P$  on which the predicate symbols in  $P$  depend.
5.  $P^-$  denotes the set of clauses in  $P$  whose head contains a predicate symbol from  $\text{Neg}_P^*$ .

**Definition 2** A program  $P$  is called  $\Phi^*$ -*accessible* if and only if there exists a level mapping  $l$  for  $P$  and a model  $I$  for  $P$  which is a supported model of  $P^-$ , such that the following condition holds. For each clause  $A \leftarrow L_1, \dots, L_n$  in  $\text{ground}(P)$ , we either have  $I \models L_1 \wedge \cdots \wedge L_n$  and  $l(A) > l(L_i)$  for all  $i = 1, \dots, n$  or there exists  $i \in \{1, \dots, n\}$  such that  $I \not\models L_i$  and  $l(A) > l(L_i)$ .

The  $\Phi^*$ -accessible programs are a common generalization of acyclic, locally hierarchical [3] and acceptable [2] programs. In [6], the authors gave a unified treatment of these classes of programs by means of operators in various three-valued logics.

**Definition 3** Let  $X$  be a set and let  $\Gamma$  be a partially ordered set with least element 0. We call

$(X, d, \Gamma)$  (or simply  $(X, d)$ ) a *generalized ultrametric space* if  $d : X \times X \rightarrow \Gamma$  is a function such that for all  $x, y, z \in X$  and all  $\gamma \in \Gamma$  we have:

- (Ui)  $d(x, y) = 0$  implies  $x = y$ .
- (Uii)  $d(x, x) = 0$ .
- (Uiii)  $d(x, y) = d(y, x)$ .
- (Uiv) Whenever  $d(x, y) \leq \gamma$  and  $d(y, z) \leq \gamma$ , we have  $d(x, z) \leq \gamma$ .

Generalized ultrametrics have been studied in the context of logic programming semantics in [7, 15, 16]. If  $d$  satisfies conditions (Ui), (Uiii) and (Uiv) only, we call  $(X, d)$  a *dislocated generalized ultrametric space* or simply a *d-ultrametric space*.

## A Generalized Priess-Crampe & Ribenboim Fixed-Point Theorem

**Definition 4** Let  $(X, d, \Gamma)$  be a d-ultrametric space. For  $0 \neq \gamma \in \Gamma$  and  $x \in X$ , the set  $B_\gamma(x) := \{y \in X \mid d(x, y) \leq \gamma\}$  is called a  $(\gamma)$ -ball in  $X$  with centre  $x$ . A d-ultrametric space is called *spherically complete* if, for any chain  $(\mathcal{C}, \subseteq)$  of non-empty balls in  $X$ , we have  $\bigcap \mathcal{C} \neq \emptyset$ . A function  $f : X \rightarrow X$  is called

- (1) *non-expanding* if  $d(f(x), f(y)) \leq d(x, y)$  for all  $x, y \in X$ ,
- (2) *strictly contracting on orbits* if  $d(f^2(x), f(x)) < d(f(x), x)$  for every  $x \in X$  with  $x \neq f(x)$ , and
- (3) *strictly contracting* if  $d(f(x), f(y)) < d(x, y)$  for all  $x, y \in X$  with  $x \neq y$ .

We will need the following observations, which are well-known for ordinary ultrametric spaces, see [14].

**Lemma 5** Let  $(X, d, \Gamma)$  be a d-ultrametric space. For  $\alpha, \beta \in \Gamma$  and  $x, y \in X$  the following statements hold.

- (1) If  $\alpha \leq \beta$  and  $B_\alpha(x) \cap B_\beta(y) \neq \emptyset$ , then  $B_\alpha(x) \subseteq B_\beta(y)$ .
- (2) If  $B_\alpha(x) \cap B_\alpha(y) \neq \emptyset$ , then  $B_\alpha(x) = B_\alpha(y)$ .
- (3)  $B_{d(x,y)}(x) = B_{d(x,y)}(y)$ .

**Proof:** Let  $a \in B_\alpha(x)$  and  $b \in B_\alpha(x) \cap B_\beta(y)$ . Then  $d(a, x) \leq \alpha$  and  $d(b, x) \leq \alpha$ , hence  $d(a, b) \leq \alpha \leq \beta$ . Since  $d(b, y) \leq \beta$ , we have  $d(a, y) \leq \beta$ , hence  $a \in B_\beta(y)$ , which proves the first statement. The second follows by symmetry and the third by replacing  $\alpha$  by  $d(x, y)$ . ■

The following theorem gives a partial unification of a theorem of Matthews [12, Theorem 5, Page 20] and the Priess-Crampe & Ribenboim theorem. The proof of the latter theorem given in [14] in fact carries over directly to our more general setting of d-ultrametrics.

**Theorem 6** Let  $(X, d, \Gamma)$  be a spherically complete d-ultrametric space and let  $f : X \rightarrow X$  be non-expanding and strictly contracting on orbits. Then  $f$  has a fixed point. If  $f$  is strictly contracting on  $X$ , then the fixed point is unique.

**Proof:** Assume that  $f$  has no fixed point. Then for all  $x \in X, d(x, f(x)) \neq 0$ . We define the set  $\mathcal{B}$  by  $\mathcal{B} = \{B_{d(x, f(x))}(x) \mid x \in X\}$ , and note that each ball in this set is non-empty. We also note that because  $d(x, y) \leq d(x, y) = d(y, x)$ , and using (Uiv), we have  $d(x, x) \leq d(x, y)$  for all  $x, y \in X$ , and it follows easily from this that  $B_{d(x, f(x))}(x) = B_{d(x, f(x))}(f(x))$  by Lemma 5. Now let  $\mathcal{C}$  be a maximal chain in  $\mathcal{B}$ . Since  $X$  is spherically complete, there exists  $z \in \bigcap \mathcal{C}$ . We show that  $B_{d(z, f(z))}(z) \subseteq B_{d(x, f(x))}$  for all  $x \in X$  and hence, by maximality, that  $B_{d(z, f(z))}(z)$  is the smallest ball in the chain. Let  $B_{d(x, f(x))}(x) \in \mathcal{C}$ . Since  $z \in B_{d(x, f(x))}(x)$ , and noting our earlier observation that  $B_{d(x, f(x))}(x) = B_{d(x, f(x))}(f(x))$  for all  $x$ , we get  $d(z, x) \leq d(x, f(x))$  and  $d(z, f(x)) \leq d(x, f(x))$ . By non-expansiveness of  $f$ , we get  $d(f(z), f(x)) \leq d(z, x) \leq d(x, f(x))$ . It follows by (Uiv) that  $d(z, f(z)) \leq d(x, f(x))$  and therefore that  $B_{d(z, f(z))}(z) \subseteq B_{d(x, f(x))}(x)$  by Lemma 5 for all  $x \in X$ , since  $x$  was chosen arbitrarily. Now, since  $f$  is strictly contracting on orbits,  $d(f(z), f^2(z)) < d(z, f(z))$ , and therefore  $z \notin B_{d(f(z), f^2(z))}(f(z)) \subseteq B_{d(z, f(z))}(f(z))$ . By Lemma 5, this is equivalent to  $B_{d(f(z), f^2(z))}(f(z)) \subseteq B_{d(z, f(z))}(z)$ , which is a contradiction to the maximality of  $\mathcal{C}$ . So  $f$  has a fixed point.

Now let  $f$  be strictly contracting on  $X$  and assume that  $x, y$  are two distinct fixed points of

$f$ . Then we get  $d(x, y) = d(f(x), f(y)) < d(x, y)$  which is impossible. So the fixed point of  $f$  is unique in this case. ■

We note that if  $d$  is a d-ultrametric, we can generate an associated generalized ultrametric  $d'$  in the usual sense by defining  $d'(x, y) = d(x, y)$  whenever  $x \neq y$  and setting  $d'(x, x) = 0$  for all  $x$ . Doing this, however, does not simplify our main application, which is below, and one then has to check that spherical completeness is preserved in generalizing the theorem of Priess-Crampe & Ribenboim. Since distance functions  $d$  such that  $d(x, x)$  is not necessarily equal to 0 do arise naturally in computing, and we consider one next, we prefer to stay with the d-ultrametric and not pass to an ultrametric.

### An Application of Theorem 6: $\Phi^*$ -accessible programs

In the following,  $P$  is a  $\Phi^*$ -accessible program which satisfies the defining conditions with respect to a model  $I$  and a level mapping  $l : B_P \rightarrow \gamma$ . We let  $\Gamma$  denote the set  $\{2^{-\alpha} \mid \alpha \leq \gamma\}$  ordered by  $2^{-\alpha} < 2^{-\beta}$  iff  $\beta < \alpha$ , and denote  $2^{-\gamma}$  by 0.

For  $J, K \in I_P$ , we now define  $d(K, K) = 0$ , and  $d(J, K) = 2^{-\alpha}$ , where  $J$  and  $K$  differ on some atom  $A \in B_P$  of level  $\alpha$ , but agree on all ground atoms of lower level. As was shown in [16],  $(I_P, d)$  is a spherically complete generalized ultrametric space. For  $K \in I_P$ , we denote by  $K'$  the set  $K$  restricted to the predicate symbols in  $\text{Neg}_P^*$ . By analogy with [5], we now define for all  $J, K \in I_P$ :  $d_1(J, K) = d(J', K')$  and  $d_2(J, K) = d(J \setminus J', K \setminus K')$ . Finally, define a function  $f : I_P \rightarrow \Gamma$  by  $f(K) = 0$  if  $K \setminus K' \subseteq I$  and otherwise  $f(K) = 2^{-\alpha}$ , where  $\alpha$  is the smallest ordinal such that there is an atom  $A \in K \setminus K'$  with  $l(A) = \alpha$  and  $A \notin I$ . Finally, we define  $\varrho(J, K) = \max\{d_1(J, I), d_1(K, I), d_2(J, K), f(J), f(K)\}$  for all  $J, K \in I_P$ .

**Proposition 7**  $(I_P, \varrho)$  is a spherically complete d-ultrametric space.

**Proof:** (Ui), (Uiii) and (Uiv) we leave to the reader. For spherical completeness, let  $(B_\alpha)$  be a (decreasing) chain of balls in  $X$  with centres  $I_\alpha$ .

Let  $K$  be the set of all atoms which are *eventually* in  $I_\alpha$ , that is, the set of all  $A \in B_P$  such that there exists some  $\beta$  with  $A \in I_\alpha$  for all  $\alpha \geq \beta$ . We show that for each ball  $B_{2^{-\alpha}}(I_\alpha)$  in the chain we have  $d(I_\alpha, I) \leq 2^{-\alpha}$ , which suffices to show that  $K$  is in the intersection of the chain. Indeed, it is easy to see by the definition of  $\varrho$  that all  $I_\beta$  with  $\beta > \alpha$  agree on all atoms of level less than  $\alpha$ . Hence, by definition of  $K$  we obtain that  $K$  and  $I_\alpha$  agree on all atoms of level less than  $\alpha$  as required. ■

The next proposition is analogous to [5, Proposition 7.1].

**Proposition 8** Let  $P$  be  $\Phi^*$ -accessible with respect to a level mapping  $l$  and a model  $I$ . Then for all  $J, K \in I_P$  with  $J \neq K$  we have  $\varrho(T_P(J), T_P(K)) < \varrho(J, K)$ . In particular we have the following:

- (i)  $d_1(T_P(J), I) < d_1(J, I)$ .
- (ii)  $f(T_P(J)), f(T_P(K)) < \varrho(J, K)$ .
- (iii)  $d_2(T_P(J), T_P(K)) < \varrho(J, K)$ .

**Proof:** It suffices to prove properties (i), (ii) and (iii). For convenience, we identify  $\text{Neg}_P^*$  with the subset of  $B_P$  containing predicate symbols from  $\text{Neg}_P^*$ .

(i) First note that  $d_1(T_P(J), I) = d_1(T_{P^-}(J), I)$  since  $d_1$  only depends on the predicate symbols in  $\text{Neg}_P^*$ . Let  $d(J, I) = 2^{-\alpha}$ . We show that  $d(T_{P^-}(J), I) \leq 2^{-(\alpha+1)}$ . We know that  $J'$  and  $I'$  agree on all ground atoms of level less than  $\alpha$  and differ on an atom of level  $\alpha$ . It suffices to show now that  $T_{P^-}(J)'$  and  $I'$  agree on all ground atoms of level less than or equal to  $\alpha$ .

Let  $A$  be a ground atom in  $\text{Neg}_P^*$  with  $l(A) \leq \alpha$  and suppose that  $T_{P^-}(J)$  and  $I$  differ on  $A$ . Assume first that  $A \in T_{P^-}(J)$  and  $A \notin I$ . Then there must be a ground instance  $A \leftarrow L_1, \dots, L_m$  of a clause in  $P^-$  such that  $J \models L_1 \wedge \dots \wedge L_m$ . Since  $I$  is a fixed point of  $T_{P^-}$ , and using Definition 2, there must also be a  $k$  such that  $I \not\models L_k$  and  $l(L_k) < \alpha$ . Note that the predicate symbol in  $L_k$  is contained in  $\text{Neg}_P^*$ . So we obtain  $I \not\models L_k$ ,  $J \models L_k$  and  $l(L_k) < \alpha$  which is a contradiction to the assumption that  $J$  and  $I$  agree on all atoms in  $\text{Neg}_P^*$  of level less than  $\alpha$ . Now assume that  $A \in I$  and  $A \notin T_{P^-}(J)$ . It follows

that there is a ground instance  $A \leftarrow L_1, \dots, L_m$  of a clause in  $P^-$  such that  $I \models L_1 \wedge \dots \wedge L_m$  and  $l(A) > l(L_1), \dots, l(L_m)$  by Definition 2. But then  $J \models L_1 \wedge \dots \wedge L_m$  since  $J$  and  $I$  agree on all atoms of level less than  $\alpha$  and consequently  $A \in T_{P^-}(J)$ . This contradiction establishes (i).

(ii) It suffices to show this for  $K$ . Assume  $\varrho(J, K) = 2^{-\alpha}$ . We show that  $f(T_P(K)) \leq 2^{-(\alpha+1)}$ , for which in turn we have to show that for each  $A \in T_P(K)$  not in  $\text{Neg}_P^*$  with  $l(A) \leq \alpha$  we have  $A \in I$ . Assume that  $A \notin I$  for such an  $A$ . Since  $A \in T_P(K)$ , there is a ground instance  $A \leftarrow L_1, \dots, L_m$  of a clause in  $P$  with  $K \models L_1 \wedge \dots \wedge L_m$ . Since  $A \notin I$ , there must also be a  $k$  with  $I \not\models L_k$  and  $l(A) > l(L_k)$  by Definition 2. If the predicate symbol of  $L_k$  belongs to  $\text{Neg}_P^*$  then, since  $K$  and  $I$  agree on all atoms in  $\text{Neg}_P^*$  of level less than  $\alpha$ , we obtain  $K \not\models L_k$  which contradicts  $K \models L_1 \wedge \dots \wedge L_m$ . If the predicate symbol in  $L_k$  does not belong to  $\text{Neg}_P^*$ , then  $L_k$  is an atom and since  $f(K) \leq 2^{-\alpha}$  we obtain  $I \models L_k$ , which is again a contradiction.

(iii) Let  $\varrho(J, K) = 2^{-\alpha}$ , let  $A$  be not in  $\text{Neg}_P^*$  with  $l(A) \leq \alpha$  and  $A \in T_P(J)$ . By symmetry, it suffices to show that  $A \in T_P(K)$ . Since  $A \in T_P(J)$ , we must have a ground instance  $A \leftarrow L_1, \dots, L_m$  of a clause in  $P$  with  $J \models L_1 \wedge \dots \wedge L_m$ . If  $I \models L_1 \wedge \dots \wedge L_m$ , then  $l(L_k) < l(A) \leq \alpha$  for all  $k$ , and since  $J$  and  $K$  agree on all atoms of level less than  $\alpha$  we obtain  $K \models L_1 \wedge \dots \wedge L_m$ , and hence  $A \in T_P(K)$ . If there is some  $L_k$  such that  $I \not\models L_k$ , then without loss of generality  $l(L_k) < l(A) \leq \alpha$  by Definition 2. Now, if the predicate symbol of  $L_k$  belongs to  $\text{Neg}_P^*$  then, since  $d_1(J, I) \leq 2^{-\alpha}$ , we obtain from  $J \models L_k$  that  $I \models L_k$  which is a contradiction. Also, if the predicate symbol of  $L_k$  does not belong to  $\text{Neg}_P^*$ , then  $L_k$  is an atom and since  $f(J) \leq 2^{-\alpha}$ , we obtain  $I \models L_k$ , again a contradiction. This establishes (iii). ■

We are now in a position to prove our main result.

**Theorem 9** Let  $P$  be a  $\Phi^*$ -accessible program. Then  $P$  has a unique supported model.

**Proof:** By Proposition 8,  $T_P$  is strictly contracting with respect to  $d_3$ , which in turn is a spherically complete d-ultrametric by Proposition 7.

So by Theorem 6, the operator  $T_P$  must have a unique fixed point which yields a unique supported model for  $P$ . ■

## Conclusion

This work is part of an ongoing programme of research being undertaken by the authors in investigating the extent to which the methods of domain theory and denotational semantics can be applied to logic programming, nonmonotonic reasoning and artificial intelligence. The focus of much of this work is on the fixed points of various operators which are associated with programs written in these paradigms, since the former provide one with a semantics (the fixed-point semantics) for the latter. Such methods depend heavily on ideas and techniques drawn from topology as illustrated in this paper, and this line of research is being further pursued in [8, 9].

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